Ace PLCs



Velocio's Ace PLCs

Ace PLCs are members of the Velocio's groundbreaking series of programmable logic controllers. These PLCs introduce revolutionary new concepts, capabilities, performance and ease of use features to the automation market. They constitute a generational leap over the staid products that have comprised the PLC world for years.

Ace PLCs are the small, stand alone members of the Velocio family. They brings incredible power, in a very small package and at a very low price. Many control system applications require 36 points of IO or less, all located very close to the PLC. For those applications, Aces are the Velocio PLCs that fit the requirements.

Ace PLCs are programmable, using Velocio's vBuilder software. The program development interface between the PC running vBuilder and an Ace is a standard USB communications cable. Through this USB cable, the Ace PLC can be programmed, debugged and deployed.

Ace PLCs interface a variety of inputs and outputs. Certain models have additional communications ports for interfacing HMIs, cellular modems, other PLCs and other devices.

The functionality available for incorporation into your application program is very encompassing and easy to implement.

In addition to the features and interfaces common to most PLCs, Ace PLCs incorporate a number of advanced features. Some of these features include high speed stepper motion control of up to three motors simultaneously, PWM (pulse width modulation), PID control, high speed pulse counter inputs, configurable digital input debounce and custom communications under program control.

The Ace's small size is another key feature. High end automation capabilites are packed into a PLC that fits in a shirt pocket. For those systems with limited availability of space, the Ace can provide a solution.



Applications

- Machine control
- Process control
- Motion system control
- Automated Test
- Internet of Things
- Integration into standard products

Features

- Up to 36 Inputs and Outputs
- USB connection to PC and other Host devices
- RS232/RS485 on some models
- Smallest physical footprint of any PLC
- High end software features that are easy to use
- Graphical program development in flow charts or ladder
 Interactive, graphical debug functionality
 - Software reusablity
- Subroutines, PID, motion, statistics & many more
- High speed pulse and direction motion control of up to 3 stepper or servo motors
- PWM capability on all digital outputs

Benefits

- Enhanced and efficient development process
- Reduced system cost
- Reduced development time
- Improved reliability
- Embeddable within product
- Rapid development and deployment

Focus on Safety



Velocio PLCs are general purpose devices, designed to provide an applications engineer or technician the capability to easily configure, program and make operational, specific projects of interest. Those specific applications can involve nearly anything and may have aspects that might be dangerous. Providing a safe operating environment for personnel and equipment is your responsibility and should be your primary goal during system design and installation. Control systems can fail. You should not rely on the control system alone to provide for a safe operating environment. External design features, including electromechanical devices, physical barriers and independent safety systems may be required to provide protection for any part of a system that poses a potential safety concern. Each application is different, so there may be special requirements for your application. Make sure you follow all national, state and local governement requirements for the proper installation and use of your equipment

Safety as Part of the Design Process

The best way to provide a safe operating environment is to make the safety of personnel and equipment a part of the design process. You should consider every element and feature of your system to determine which areas require attention to ensure personnel safety and to protect related equipment. In addition to your personal evaluation, be sure to take into account the following.

- NEMA The National Electrical Manufacturing Association has a number of relevant standards and guidelines.
- NFPA The National Fire Protections Association safety documents
- NEC The National Electrical Code defines regulations and standards for electrical wiring
- Local and State Agencies Many local governments have additional regulations
- Your company standard Many companies have standards that are specific to the company

Standard Safety

While every application is different, if you have an application that presents potential safety risks, you should take (at least) the following list into consideration.

- · Physical barriers keep people, including their hands and legs away from moving parts
- · Light curtains or other sensors that detect personnel moving into areas that are potentially unsafe
- Emergency shut down circuits that are electrically separate from the PLC
- System power disconnect

• Orderly shutdown - orderly, controlled shut down of equipment when triggered by the sensing of an unsafe or irregular condition, or initiated by an operator

For your specific application, there my be other, or additional considerations. The key is to purposely take the time to consider, during the design process - "What could go wrong" - and then design in barriers of mechanisms that will protect personnel and equipment from the effects of what could go wrong. Keep safety in mind throughout the process and, if additional concerns crop up, address them.

At the end of development, again look for potential problem areas and address them appropriately yet again. While doing so, consider that it is possible that you made a mistake or didn't cover a condition in your design. Ask the question, "What might happen if my design has a error or an unhandled condition?". Then make sure that safety features cover that case.

The most important aspect of any application is safety. Its your responsibility to make safety paramount.

Flavors of Ace



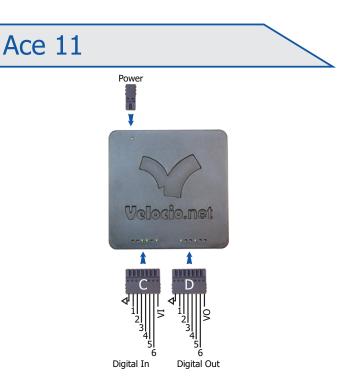
There are a growing number of models of Ace PLCs. The units vary with respect to input/output (IO) configuration, number of ports and communications capabilities. They range from the simplest unit, the Ace 11, to higher end units with a great deal of functionality.

				109 In 0-5 Anz	volt 109 In 0-1 Ana	ovolt 109 In 0-20 Anal	umAmp 109 Out 16 The	bit	f Analog Ir 32 RS2	1,85
	: ait	al In Digit	tal Out Anal	109 In 0-2	109 In 0-1	109 In 0.	log Out 1	rm In L	32 22	521R5485
	Dig	Dig	And	And	Arie	And	The	RSE	R5r	
Ace 11	6	6								
Ace 1430	6	12							1	
Ace 1450	6	12					2		1	
Ace 1600	3	6						1		
Ace 1630v5	3	3	3					1		
Ace 1630v10	3	3		3				1		
Ace 1630c	3	3			3			1		
Ace 1700	12	24								
Ace 1701	8	24						1		
Ace 1800	18	18								
Ace 1801	14	18						1		
Ace 1802 NEW!	18	14						1		
Ace 22	12	12								
Ace 222v5	12	12	12							
Ace 222v10	12	12		12						
Ace 222c	12	12			12					
Ace 3090v5	6	18	3				4	1		
Ace 3090v10	6	18		3			4	1		
Ace 3090c	6	18			3		4	1		
Ace 5150v5	12	12	3					1		
Ace 5150v10	12	12		3				1		
Ace 5150c	12	12			3			1		
Ace 7096v5	6	12	4			2	4	2		
Ace 7096v10	6	12		4		2	4	2		
Ace 7096c	6	12			4	2	4	2		



The Ace 11 is a low IO count, least expensive member of the family. In addition to basic digital inputs and outputs, it is designed for motion control, PWM outputs and high speed pulse counting.

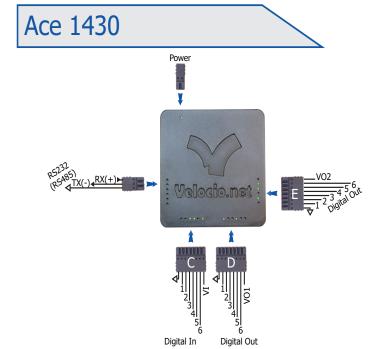
- 6 Digital Inputs
 - Protected, 3-30VDC
- High speed pulse counting capability
- 6 Digital Outputs
- Sinking transistor outputs
- Step and direction motion control enabled (3 maximum)
- PWM capable on all outputs
- USB programming port
- USB port Modbus RTU slave enabled



Ace 1430

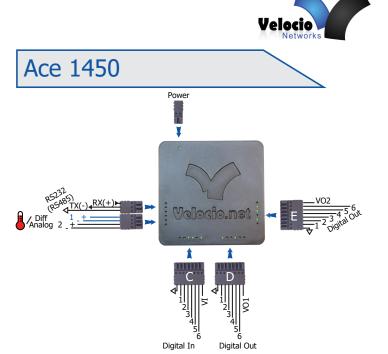
The Ace 1430 includes IO interfaces for 6 digital inputs, 12 digital outputs and a serial port that is program configurable as either RS232 or RS485.

- 6 Digital Inputs
 - Protected, 3-30VDC
 - High speed pulse counting capability
- 12 Digital Outputs
- Sinking transistor outputs
- Step and direction motion control enabled (3 maximum)
- PWM capable on all outputs
- Serial port configurable as RS232 or RS485
- Modbus RTU slave
- Custom message communications
- USB programming port
- USB port Modbus RTU slave enabled



The Ace 1450 includes IO interfaces for 6 digital inputs, 12 digital outputs, 2 thermocouple/differential voltage inputs and a serial port that is program configurable as either RS232 or RS485.

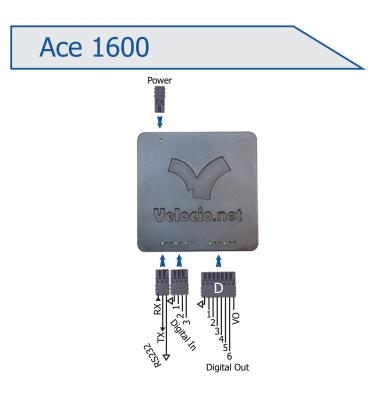
- 6 Digital Inputs
- Protected, 3-30VDC
- High speed pulse counting capability
- 12 Digital Outputs
- Sinking transistor outputs
- Step and direction motion control enabled (3 maximum)
- PWM capable on all outputs
- 2 thermocouple/differential voltage inputs
- J, K, T or N thermocouple
- 16 bit differential voltage input selectable for +/-0.256V, 0.512V, 1,024V and 2.048V ranges
- Serial port configurable as RS232 or RS485
 - Modbus RTU slave
- Custom message communications
- USB programming port
- USB port Modbus RTU slave enabled

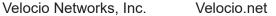


Ace 1600

The Ace 1600 is the lowest cost Ace PLC with an RS232 port. It provides 3 digital inputs and 6 digital outputs, along with that RS232 port. In addition to basic digital inputs and outputs, it is designed for motion control, PWM outputs and high speed pulse counting.

- 3 Digital Inputs
 - Protected, 3-30VDC
- High speed pulse counting capability
- 6 Digital Outputs
- Sinking transistor outputs
- Step and direction motion control enabled (3 maximum)
- PWM capable on all outputs
- RS232 port
- Modbus RTU slave
- Custom message communications
- USB programming port
- USB port Modbus RTU slave enabled



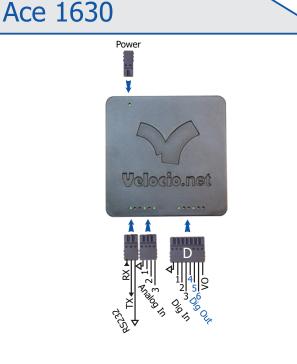


June 2019

Ace 1630

The Ace 1630 provides 3 digital inputs, 3 digital outputs and 3 analog inputs. It also includes an RS232 port for connection to HMIs and other devices. In addition to basic digital inputs and outputs, it is designed for motion control, PWM outputs and high speed pulse counting.

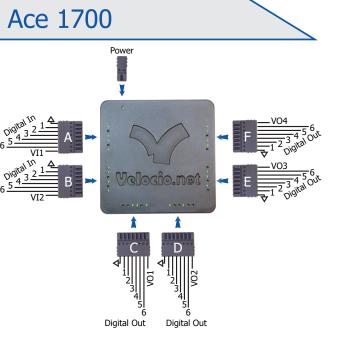
- **3 Digital Inputs**
 - Protected, 3-30VDC -
 - High speed pulse counting capability
 - **3 Digital Outputs**
 - Sinking transistor outputs
 - _ Step and direction motion control enabled
 - PWM capable on all outputs
 - **3 Analog Inputs**
 - Ace 1630v5 : 0-5VDC analog inputs
 - Ace 1630v10 : 0-10VDC analog inputs
 - Ace 1630c : 0-20mA analog inputs (also used for 4-20mA signals)
- RS232 port
- Modbus RTU slave
- Custom message communications
- USB programming port
- USB port Modbus RTU slave enabled -



Ace 1700

The Ace 1700 provides 12 digital inputs and 24 digital outputs. In addition to basic digital inputs and outputs, it is designed for motion control, PWM outputs and high speed pulse counting.

- 12 Digital Inputs
- Protected, 3-30VDC -
- High speed pulse counting capability
- 24 Digital Outputs
- Sinking transistor outputs
- Step and direction motion control enabled (3 maximum)
- PWM capable on all outputs
- USB programming port
- USB port Modbus RTU slave enabled _

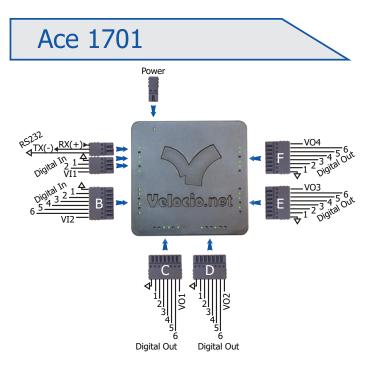






The Ace 1701 includes IO interfaces for 8 digital inputs, 24 digital outputs, and an RS232.

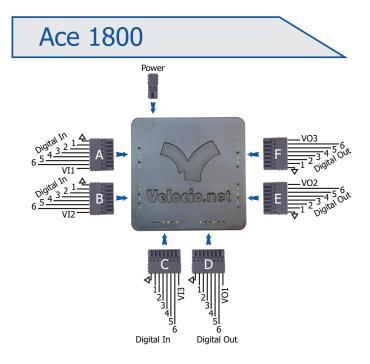
- 8 Digital Inputs -
 - Protected, 3-30VDC
 - High speed pulse counting capability
 - 24 Digital Outputs
 - Sinking transistor outputs
 - Step and direction motion control enabled (3 maximum)
 - PWM capable on all output
- RS232 port
 - Modbus RTU slave
- Custom message communications
- USB programming port
- USB port Modbus RTU slave enabled



Ace 1800

The Ace 1800 includes IO interfaces for 18 digital inputs and 18 digital outputs.

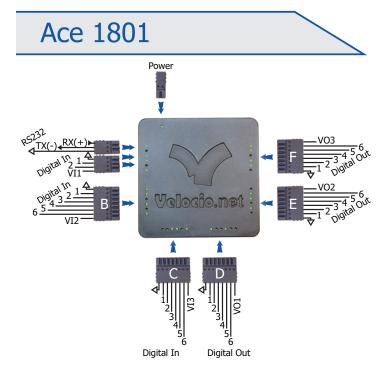
- 18 Digital Inputs -
 - Protected, 3-30VDC
- High speed pulse counting capability
- 18 Digital Outputs
- Sinking transistor outputs
- Step and direction motion control enabled (3 maximum)
- PWM capable on all outputs
- USB programming port
- USB port Modbus RTU slave enabled





The Ace 1801 includes IO interfaces for 14 digital inputs, 18 digital outputs, and an RS232.

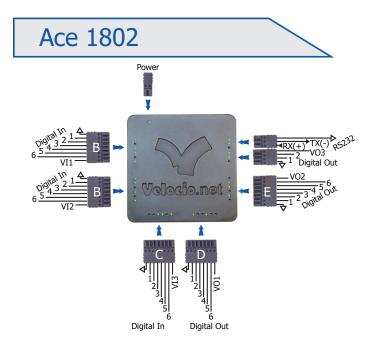
- 14 Digital Inputs -
 - Protected, 3-30VDC
- High speed pulse counting capability
- 18 Digital Outputs
- Sinking transistor outputs
- Step and direction motion control enabled (3 maximum)
- PWM capable on all output
- RS232 port
 - Modbus RTU slave
- Custom message communications
- USB programming port
- USB port Modbus RTU slave enabled



Ace 1802

The Ace 1802 includes IO interfaces for 18 digital inputs, 14 digital outputs, and an RS232.

- 18 Digital Inputs -
 - Protected, 3-30VDC
 - High speed pulse counting capability
- 14 Digital Outputs
 - Sinking transistor outputs
 - Step and direction motion control enabled (3 maximum)
 - PWM capable on all output
- RS232 port
 - Modbus RTU slave
- Custom message communications
- USB programming port
- USB port Modbus RTU slave enabled

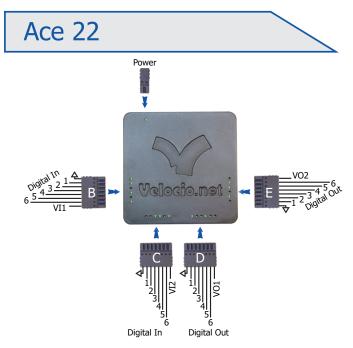


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The Ace 22 provides 12 digital inputs and 12 digital outputs. In addition to basic digital inputs and outputs, it is designed for motion control, PWM outputs and high speed pulse counting.

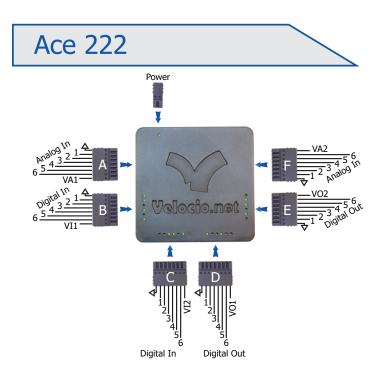
- 12 Digital Inputs
 - Protected, 3-30VDC
 - High speed pulse counting capability
- 12 Digital Outputs
 - Sinking transistor outputs
- Step and direction motion control enabled (3 maximum)
- PWM capable on all outputs
- USB programming port
- USB port Modbus RTU slave enabled



Ace 222

The Ace 222 includes IO interfaces for 12 digital inputs, 12 digital outputs and 12 analog inputs. The three different models of Ace 222 differ only in the analog signal range they are designed to interface (v5 = 0.5VDC, v10 = 0.10VDC and c = 0.20mA). In addition to basic digital inputs and outputs, it is designed for motion control, PWM outputs and high speed pulse counting.

- 12 Digital Inputs
 - Protected, 3-30VDC
- High speed pulse counting capability
- 12 Digital Outputs
- Sinking transistor outputs
- Step and direction motion control enabled (3 maximum)
- PWM capable on all outputs
- 12 Analog Inputs, 12 bit resolution
- Ace 222v5 : 0-5VDC analog inputs
- Ace 222v10 : 0-10VDC analog inputs
- Ace 222c : 0-20mA analog inputs (also used for 4-20mA signals)
 - USB programming port
- USB port Modbus RTU slave enabled



Velocio.net



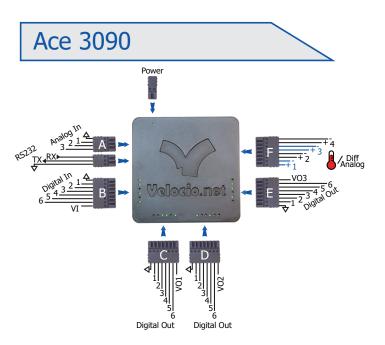
The Ace 3090 includes IO interfaces for 6 digital inputs, 18 digital outputs, 3 analog inputs, four thermocouple/differential voltage inputs and an RS232 port. The three different models of Ace 3090 differ only in the analog signal range they are designed to interface (v5 = 0-5VDC, v10 = 0-10VDC and c = 0-20mA).

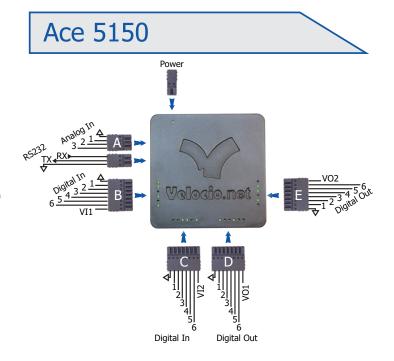
- 6 Digital Inputs
 - Protected, 3-30VDC
 - High speed pulse counting capability
 - 18 Digital Outputs
 - Sinking transistor outputs
 - Step and direction motion control enabled (3 maximum)
 - PWM capable on all outputs
 - 3 Analog Inputs, 12 bit resolution
 - Ace 3090v5 : 0-5VDC analog inputs
 - Ace 3090v10 : 0-10VDC analog inputs
 - Ace 3090c : 0-20mA analog inputs (also used for 4-20mA signals)
 - 4 thermocouple/low level differential voltage inputs
 - J, K, T or N thermocouple
 - 16 bit differential voltage input selectable for +/-0.256V,
 - 0.512V, 1,024V, and 2.048V ranges
 - RS232 port
 - Modbus RTU slave
 - Custom message communications
 - USB programming port
 - USB port Modbus RTU slave enabled

Ace 5150

The Ace 5150 includes IO interfaces for 12 digital inputs, 12 digital outputs, 3 analog inputs and an RS232 port. The three different models of Ace 5150 differ only in the analog signal range they are designed to interface (v5 = 0-5VDC, v10 = 0-10VDC and c = 0-20mA).

- 12 Digital Inputs
 - Protected, 3-30VDC
 - High speed pulse counting capability
 - 12 Digital Outputs
 - Sinking transistor outputs
 - Step and direction motion control enabled (3 maximum)
 - PWM capable on all outputs
 - 3 Analog inputs, 12 bit resolution
 - Ace 5150v5 : 0-5VDC analog inputs
 - Ace 5150v10 : 0-10VDC analog inputs
 - Ace 5150c : 0-20mA analog inputs (also used for 4-20mA signals)
- RS232 port
 - Modbus RTU slave
- Custom message communications
- USB programming port
- USB port Modbus RTU slave enabled



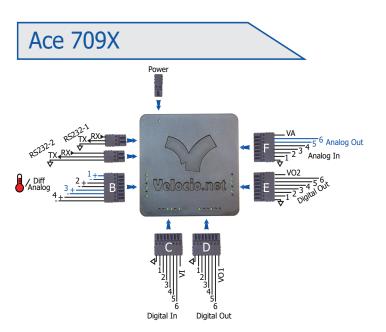


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The Ace 7096 includes IO interfaces for 6 digital inputs, 12 digital outputs, 4 analog inputs, four thermocouple/differential voltage inputs, two analog outputs and two RS232 ports. The three different models of Ace 7096 differ only in the analog signal range they are designed to interface (v5 = 0-5VDC, v10 = 0-10VDC and c = 0-20mA).

- 6 Digital Inputs
 - Protected, 3-30VDC
 - High speed pulse counting capability
 - 12 Digital Outputs
 - Sinking transistor outputs
 - Step and direction motion control enabled (3 maximum)
 - PWM capable on all outputs
- 4 Analog Inputs, 12 bit resolution
- Ace 7096v5 : 0-5VDC analog inputs
- Ace 70960v10 : 0-10VDC analog inputs
- Ace 7096c : 0-20mA analog inputs (also used for
- 4-20mA signals)
- 2 Analog Outputs
- 0-5V or 0-10 (selectable using vBuilder)
- 16 bit resolution
- 4 thermocouple/low level differential voltage inputs
- J, K, T or N thermocouple
- 16 bit differential voltage input selectable for +/-0.256V, 0.512V, 1,024V and 2.048V ranges
- 2 RS232 ports
- Modbus RTU slave
- Custom message communications
- USB programming port
 - USB port Modbus RTU slave enabled





♦ Digital Inputs :

All Ace PLCs accept some number of digital inputs. Digital inputs sense binary status, such as on/off, switch open/closed, etc. The Ace PLC can interface any DC voltage signal between 3 and 30VDC. Typical system designs utilize 5V, 12V or 24VDC power supplies, which are all within the Ace's signal range.

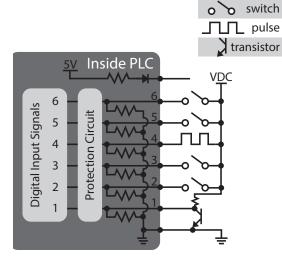
Any connection to DC voltage between 3 and 30VDC is sensed as a '1'. Any connection to ground (or voltage below 0.8VDC) or an open connection is sensed as '0'. The ground reference of the signal must be connected to the ground terminal pin next to signal 1, or to the PLC's input power ground.

The figure on the right shows a variety of typical digital input signals that may be connected to Ace digital inputs. Some of the more common ones include :

- Switches (this could be mechanical switches, buttons, limit switches, etc.)
 - Connect one side to positive DC power (from a supply whose ground is connected to the PLC ground)
 - Connect the other side of the switch to the digital input
 - Transistor signal
 - For transistor signals that supply voltage when on : connect sensor output to digital input

- For transistor signals that switch to ground when on : connect to sensor output to digital inputs & if input device does not pull high when inactive, also pull up to positive voltage through a pull up resistor

- Encoder signals
- Encoders will fall into one of the transistor signal categories listed above
- Logic level signals
- Make sure that the signal's ground reference is connected to the PLC ground. Connect of input.
- Make sure that the signal switches high and low.



The last pin on each digital input port connector provides a voltage (connected to the 5V power input, through a 10 ohm resistor and a diode) which is used by the Optocouple Input Terminal modules. It can also be used to supply "wetting voltage" to dry contact inputs.

Internally, as part of the protection circuit, each digital input is pulled to ground through a 10K ohm resistor. This pull down resistor ensures that the digital input shows up as inactive when nothing is connected or the connection just sources voltage when it is active.

Do not connect external power to the
voltage pin (pin 8) on the digital input
port.

Ace digital inputs (and the Ace CPU) are very fast. For a small program, the logic scan and input scan can occur 5 times per millisecond. At this rate, mechanical contact bounce can signal the program

Input / Output	Name	Signal	Debounce (ms.)
Input bit Input i16	InBitB1	B1	0
_	InBitB2	B2	5
Output bit	InBitB3	B3	5
Output ui16	InBitB4	B4	0
Register	I-D+DF	PE	n

that an input is changing rapidly - which can be a problem. To alleviate this situation, vBuilder has an option to allow you to set a debounce time on digital inputs. A debounced digital input will not report a change of state until that change has been continuous for the set debounce time. Note that debounce does not apply to inputs configured as high speed pulse counter inputs.

Using vBuilder, one high speed pulse counter can be configured for basic high speed pulse counting (one digital input), or quadrature pulse counting (two digital inputs). The same signal level requirements apply, as listed above.

For digital inputs that are AC signals, the Ace's digital input ports can be connected to Velocio Optocoupled Input Terminal Block modules. These modules interface 24VAC or 120VAC signals. A cable, supplied with each terminal block module is then connected to the Ace digital input port. The Optocoupler Input Terminal Block modules convert the AC signals to the proper DC levels to the PLC.



♦ Digital Outputs :

All Ace PLCs have some number of digital outputs. Ace digital outputs are sinking transistor outputs - which means that they provide the ground connection turn on a load. When switched on under program control, they complete the circuit to turn on any connected DC device up to 30VDC and (nominally) 300mA. The actual current limit is shown in the figure at the bottom of this page and is dependent on the number of digital outputs that are on simultaneous and their duty cycle.

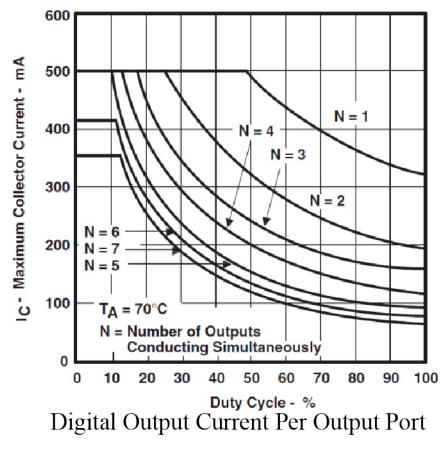
Each ouput includes diode snubber protection, for inductive load (solenoids, relays, etc.) protection. The supply voltage, up to 30VDC, which is connected to the load devices, must be connected to the VO terminal pin, next to output 6 of the output port, to enable this protection. All loads connected to a digital output port should be connected to the same DC supply. The load power supply ground must be connected to the ground (next to signal 1) of the output port.

Each output is connected, through a 33K ohm resistor to the VO terminal pin (next to output 6). This acts as a weak pull up. When the output is off (logic state 0), the output will be pulled up to the voltage at the VO terminal. If no power supply connection is made to the VO terminal, the voltage at the VO terminal will come through a 10 ohm resistor and an isolation diode, resulting in a voltage approximately 0.7V below the 5V supply to the PLC. This is enough to allow the PLC outputs to directly interface TTL circuits. If voltage is connected from an external source to the VO terminal, inactive outputs will pull up to the external source voltage.

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If AC power, or higher power DC needs to be switched, the Ace's digital output ports can be connected to a Velocio Relay Terminal Block module

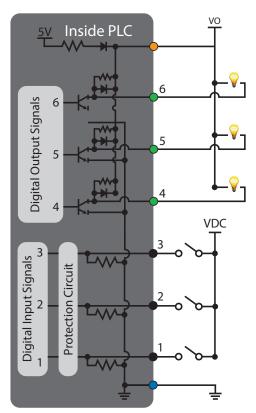
or Transistor Terminal modules (sinking or sourcing, DC only), through a short standard cable, supplied with the module. With these modules, higher currents and in the case of the Relay Modules, up to 250VAC, can be switched under program control. The cable diagram connection to the PLC digital output port pluggable connector is illustrated in the Relay Terminal Block module documentation.





\diamond **Combination Digital Input and Output Ports**

The Ace 1630 has a port (the D port) that has three digital inputs and three digital outputs. The diagram for that port is shown on the right. As you can see, the ground reference is common to the digital inputs and outputs. There is a VO connection on pin 8. The digital input and output characteristics as the same as describe previously, under the Digital Input and Digital Output sections.



Inside

PLC

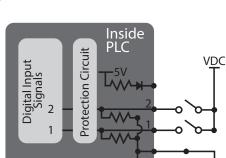
VDC

\diamond **Digital Inputs for Ace 1600**

The digital inputs on the Ace 1600 PLC are located on a 4 pin connector, which is the second half of the C port. The RS232 port is the first half of the C port. Since this is a minimal IO count PLC, with RS232, the digital port maximizes the number of digital inputs available (3) by eliminating the VI voltage pin.

\Diamond Digital Inputs on Other Combination RS232/Digital Input Ports

Four pin digital input port connectors, other than the Ace 1600, have the same connections as the standard 8 pin/6 digital input signal ports. They simply have only two digital inputs. They do have the signal ground on pin 1 and VI voltage ouput on pin 4.





rotection Circuit

Digital Input Signals

3

2



♦ Analog Inputs :

Ace PLCs are available with some number of general analog inputs. Ace PLC analog input interfaces are available for either 0-5VDC, 0-10VDC or 0-20mA.

Analog inputs are normally used to connect to transducer outputs. Such transducers measure some physical parameter, such as pressure, temperature, liquid level, position, pH level, or other such continuously variable measurement. The transducer signal output should be connected to a signal input on the Ace analog port and the transducer return or ground reference line must be connected to the PLC ground, next to signal 1 (or otherwise connected to the PLC's ground).

Ace PLCs with current input analog input ports (part number ending in 'c') should be used for analog current signals between 0 and 20 mA. The two most common type of current signals are 4-20 mA and 0-20 mA.

Full range analog signals will convert to a value between 0 and 4095 (12 bits). For 4-20mA inputs, the converted value will be between 820 and 4095. The Scale function in vBuilder can be used to automatically convert the signal value to meaningful data.

For PLCs that have a full 8 position port dedicated to analog inputs, the pin next to

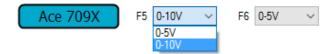
the sixth input is connected to the PLC's internal 5V, through a 10 ohm resistor and a diode. This is provided to power a future analog input simulator. It servers no other purpose and should remain unconnected for application use. Analog input ports that do not occupy the full 8 position port do not have this connection.

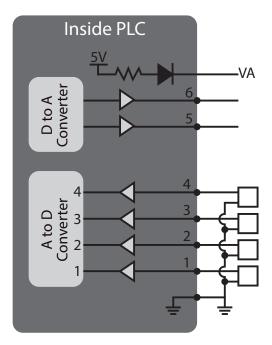
Organization Analog Inputs and Analog Outputs

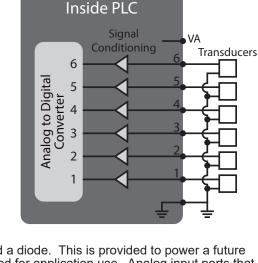
Certain Ace PLCs have a single connector with both analog inputs and outputs. The connections are as shown on the diagram at the right.

The first few signals on the port are analog inputs. They are 12 bit analogs, described in the analog input description. Typically, there are either 3 or 4 analog inputs in a combination port

The last signals on a combination port are analog outputs. For the Ace 7096 these are 16 bit resolution outputs, which can be individually configured, using vBuilder for either 0-5V or 0-10V operation, as shown below.









♦ Thermocouple/16 bit Differential Low Voltage Analog Inputs

Several Ace PLC's include interfaces that are configurable for either providing thermocouple interfaces or serving as analog inputs for differential analog signals. These signal inputs can be individually configured, in vBuilder, for either thermocouple or differential voltage ranges.

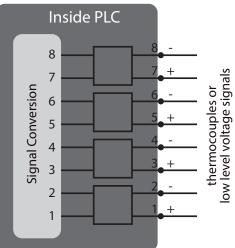
For interfacing to thermocouples, these inputs can be configured for J, K, T or N type thermocouples. Connect each thermocouple to one of the four wire pairs shown in the diagram on the right. The negative (red) wire should be connected to the negative input (indicated by a '-' sign on the diagram). The positive wire should be connected to the positive connection.

Each differential input can also be used to measure low level differential voltage signals. The following ranges are available :

- +/- 0.256V
- +/- 0.512V
- +/- 1.024V
- +/- 2.048V

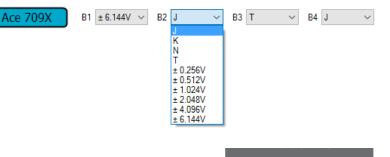
The vBuilder Setup window for the thermocouple/ differential analog configuration is shown on the right.

In operation, the signal is converted to a floating point value. That value is either temperature, in degrees Celcius, or volts.



Thermocouple / Differential Input Setup

RS232 Cable



♦ RS232 and RS232/485 Ports :

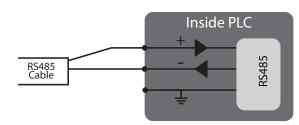
Certain Ace PLCs have RS232 ports or configurable RS232/485 ports. RS232 ports are commonly used for interfacing hardware HMI panels and other devices through Modbus RTU communications. They are also commonly used to interface cellular transceivers for internet of things applications and can be used in Custom communications mode to communicate to any device that has an RS232 port.

RS485 ports are commonly used in multi-unit systems and for longer distance communictions.

Ace PLC RS232 ports have three pin connectors. The illustration on the right shows the connections.

- Signal ground
- PLC transmit (must be connected to the receive pin of the connected device)
- PLC receive (must be connected to the transmit pin of the connected device)

Some Ace PLCs have serial ports that can be configured as either RS232 or RS485. When configured as RS232, the connections are identical to the connections shown for the dedicated RS232 ports. If the port is configured for RS485, the two connections used are the + (or A), on the same pin as the RS232's RX and the - (or B), on the middle pin or RS232's TX pin. The ground can be connected to the cable shield. However, the shield should only be connected at one end of the cable.



RS232



8

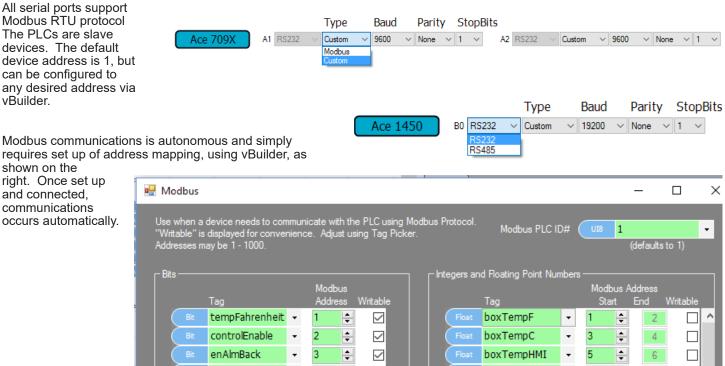
10

12

14

 \checkmark

Serial ports can be configured by vBuilder for either Modbus RTU slave or Custom communications operation. Each port can also the configured for a variety of baud rates, the number of stop bits and parity. Serial ports that can be configured for either RS232 or RS485 have another configuration selection for that purpose.



occurs automatically.

	Bit	tempFahrenheit	-	1		\checkmark		Float	boxTempF	-	1	-
	Bit	controlEnable	-	2	-	\checkmark		Float	boxTempC	•	3	+
	Bit	enAlmBack	-	3	-	\square		Float	boxTempHMI	•	5	-
	Bit	enAlmFront	-	4	-	\square		Float	ambTempHMI	•	7	-
	Bit	almBackDoor	-	5	-			Float	tempSetpointHM	•	9	*
	Bit	almFrontDoor	-	6	-			Float	compInPressure	•	11	-
	Bit	almHPress	-	7				Eloat	compOutPressu	-	13	
ed for Custom C	comm	unications. the	por	t will :	send	and re	eceive c	haract	er (ui8) arravs.	und	er pr	oara

When configured for Custon ng receive character (ui8) arrays, under program control, through the use of program blocks like those shown on the right.

Port	BO SEND		Pi	ort B0 RECEIVE	
Array to Send 😈			# Bytes Received		
Message Length (10	0)	- 1	Receive Array		
Done Sending Bit	t txDone		Minimum Break	()	
			Message Avaiable	Bit nxDone	

Wire Connections to the Ace Pluggable Terminal Blocks

Ace units come with pluggable terminal blocks, like the one shown on the on the right. Connect your wires using the larger circular holes on the top row of the orientation shown.

Looking at the connector, in the orientation shown from left to right, the eight wire positions are ground, six signal positions 1 through 6, and either a no connect or voltage connection

You simply need to strip the insulation back about 1/8 inch, insert each wire into the proper round connector hole and push the wire in. It should push in very easily and lock in place. You should not be able to pull the wire back out.

To insert fine stranded wire, insert the blade of a Velocio connector tool (screwdriver) in the rectangular hole directly below the connection hole which you wish to insert your wire. The screwdriver blade should be horizontal (in line with the long dimension of the rectangular hole). This will open the spring capture connection. Simply push your wire in, then remove the blade. If you pull the wire, it should be captured in place and will not come out.

To remove any wire from the connector, use the Velocio screwdriver connector tool. Push the blade into the rectangular slot below the wire to open the spring clamp and release the wire. Gently pull the wire out, then remove to blade.

Connecting Power

Power to the Ace PLC must be provided via a two position pluggable connector, included with the Ace unit. To connect power, insert the 5VDC and ground connections from a power supply into the plug, as shown in the figure below. When plugged into the PLC's power connector socket, the +5VDC connection is to the right, closest to the corner..

Shielded Cabling

For applications in which interconnection requires long lengths of wire/cabling in exposed areas, it is highly recommended that shielded cable be used. Long wires act as antennas and have unwanted electrical signals induced onto signal connections. Shielded cable (grounded at one end) will shield the signal wires from unwanted and potentially dangerous electomagnetic interferance.







Velocio.net





SW AHB.

3M VHB"

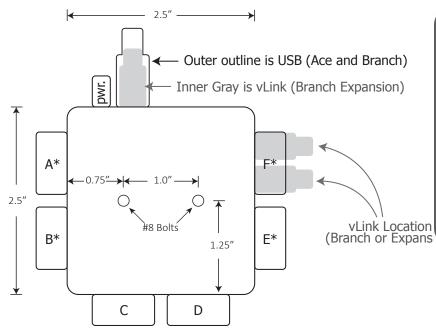
Mounting Options

Each Velocio PLC comes with a double sided adhesive pad for attaching to painted metals, plastics or glass. Using this method of attachment allows you to install the PLC in very tight and unusual environments as well as place them in typical electrical control panels. The adhesive is very strong and will provide a solid permanant attachment, unless extreme pressure is applied to break the seal.

Alternatively, Velocio PLCs are designed to add an optional vMount DIN rail mounting adapter. The vMount adapter snaps onto the bottom side of the PLC. It can then be snapped onto a standard 35mm DIN rail, or can slide onto a pair of properly spaced screws.

DIN rail mounting is illustrated on the right. The necessary hole pattern for screw mounting is shown below.











Specifications :

Hardware Specifications

		10113
Power		
	Voltage current	5.0 - 5.5VDC
	current	300mA maximum
Distal	manufa .	< 100mA typical
Digital I		
	Type: DC volt	age input
	Input range : 3 t	o 30 VDC
	Internal pull dow	n to ground : 10K ohms
		signal : 0 to 0.8V, or open connection
		signal : 2.5 to 30VDC
	Pulse counter in	
	up to th	ree pulse count or quadrature inputs
	at up to	a combined rate of 250 KHz
		able debounce : 0 to 255 milliseconds
Digital (Outputs :	
	Type : Sinking tr	ansistor
	Voltage range :	3 to 30VDC
	Current :	300 mA maximum (see curve in
	Guiront.	Digital Output section)
	Motion output p	
	un to th	ree pulse and direction outputs at up
		nbined rate of 250 KHz (maximum)
		: 1 microsecond
م <u>م</u> ام م		resistance to VO : 33Kohms
Analog	Inputs :	
	Туре :	$v_5 = 0$ to 5VDC:
		v10 = 0 to $10VDC$
		c = 0 to 20 mA
	resolution :	12 bit
	_	
Analog	Outputs :	
	Types :	selectable ; 0-5V, 0-10V
	resolution :	16 bit
Thermo	couple/Differentia	al Voltage Inputs :
	Types :	selectable ; J, K, T and N or -
		+/- 0.256V
		+/- 0.512V
		+/- 1.024V
		+/- 2.048V
	Output value :	floating point value in degrees C or V
	Sulput value .	nouting point value in degrees 0 01 V
Com		
Comm	<u>unications :</u>	
	Upstream :	USB Device
	B0 000	mini USB connector
	RS232 :	3 wire (TX, RX and ground)
	RS485	2 wire
•	baud ra	tes selectable ;
		9600 baud
		19200 baud
		38400 baud
		57600 baud
		15200 baud

Physical Dimensions : 2.5"H x 2.5"W x 0.5	" deep		
Environmental Operating temperature :	all com -40 to		s rated for
Storage temperature : Humidity :	-55 to	+125C	n-condensing
Software Specifications			
Application Program Lin Program Memory : Maximum rungs or Maximum # Subrou	function blocl tines		34K Words 4K 68
	memory bit integers		950 2,048 512
signed 16 l signed 32 l floating poi	oit integers nt numbers		512 512 256 256
Object Memory (use object word		tine data	a) 4,096
object bits object 8 Of object sign	f integers ed 16 bit gned 16 bit ed 32 bit	up to up to up to up to up to up to	65,536 8,192 4,096 4,096 2,048 2,048
Maximum # object libat Maximum # PWM of Maximum # of Step Maximum Stepper I	outputs per Motion C	all digi ontrols :	292 ital outputs
Terminal Block Connec	tions		
Terminal type	Socket		tors and pture plug
Terminal spacing :	1	2 50 m	

	Spring cage capture plug
Terminal spacing :	2.50 mm
Wire AWG	20 to 26 AWG*
* best wire fit is with 22 or 24 AW	G

parity

stop bits

•

15200 baud

selectable

selectable